



- 3 a. Draw the direct form I and direct form II representation for the given difference equation :  
 $y[n] + \frac{1}{2}y[n-1] - \frac{1}{3}y[n-3] = x[n] + 2x[n-2]$ . (06 Marks)
- b. Obtain ZIR, ZSR for the system described by difference equation :  
 $y[n] - \frac{1}{4}y[n-2] = 2x[n] + x[n-1]$   
 for given input  $x[n] = u[n]$  initial conditions  $y[-2] = 8$ ;  $y[-1] = 0$ . (06 Marks)
- c. Find the total solution for the system described by the differential equation :  
 $\frac{d^2y(t)}{dt^2} + 3\frac{dy(t)}{dt} + 2y(t) = 2x(t)$   
 Given  $x(t) = \cos t u(t)$   $y(0) = -\frac{4}{5}$   $\left. \frac{dy(t)}{dt} \right|_{t=0} = \frac{3}{5}$ . (08 Marks)

- 4 a. State and prove the following properties of DTFS  
 i) Time shifting property  
 ii) Time scaling property. (06 Marks)
- b. Find the exponential Fourier series of the waveform shown in Fig.Q4(b). (06 Marks)

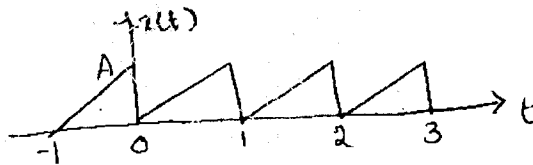


Fig.Q4(b)

- c. Find the DTFS of the signal shown in Fig.Q4(C). Also find the magnitude and space spectrum. (08 Marks)

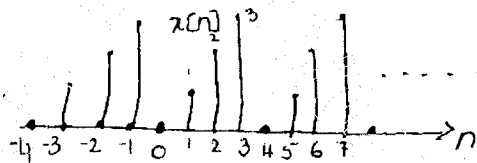


Fig.Q4(c)

**PART – B**

- 5 a. State and prove the following properties of CTFT. i) Convolution ii) Linearity. (06 Marks)
- b. Find the inverse Fourier transform of  $x(\omega)$  for the spectra shown in Fig.Q5(b). (06 Marks)

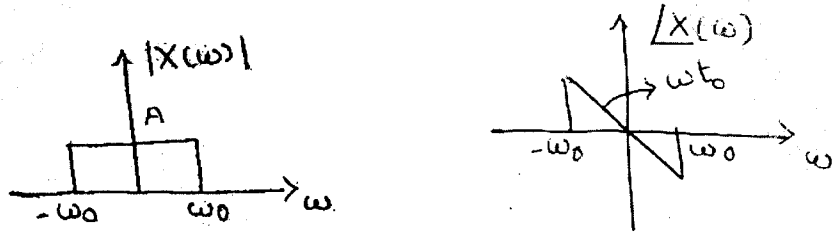


Fig.Q5(b)

- c. The input and output of a causal LIT system is described by the differential equation :  
 $\frac{d^2y(t)}{dt^2} + \frac{3dy(t)}{dt} + 2y(t) = x(t)$   
 i) Find the frequency response of the system  
 ii) Find the impulse response of the system  
 iii) What is the response of the system if  $x(t) = r^{-1} u(t)$ . (08 Marks)

- 6 a. Using the appropriate property, find the DTFT of the following signals.
- $x_1[n] = (\frac{1}{2})^n u[n-2]$
  - $x_1[n] = \left\{ \underset{\uparrow}{1} \ 2 \ 3 \ 4 \right\}$   $x_2[n] = \left\{ \underset{\uparrow}{2} \ 3 \ 4 \ 1 \right\}$ . Find  $x_1[n] * x_2[n]$ . (06 Marks)
- b. Prove that DTFT of the rectangular pulse given below is :
- $$x[n] = \begin{cases} 1 & -N_1 \leq n \leq N_1 \\ 0 & \text{otherwise} \end{cases}$$
- $$X_{(j\omega)} = \frac{\sin \Omega(N_1 + \frac{1}{2})}{\sin(\Omega/2)}$$
- (06 Marks)
- c. A causal system is represented by the difference equation is :
- $$y[n] + \frac{1}{4} y[n-1] = x[n] + \frac{1}{2} x[n-1]$$
- Use DTFT to determine the following :
- The frequency response of the system
  - The impulse response
  - Response of the system to input  $x[n] = (\frac{1}{2})^n u[n]$ . (08 Marks)
- 7 a. From the definition of z transform, find the z transform of the following signals and also specify their ROC.
- $x[n] = a^n u[-n-1]$
  - $x[n] = (\frac{1}{2})^n u[n] + (\frac{1}{3})^n u[n]$ . (06 Marks)
- b. Using the properties of z transform find the z transform of the following :
- $$x[n] = na^n u[n]$$
- $$x[n] = a^{(2n-1)} u[n+3]$$
- (06 Marks)
- c. Determine the inverse z transform of  $x(z) = \frac{3}{1-1.5z^{-1}+0.5z^{-2}}$  by using power series expansion method for : i) ROC  $|Z|>$  ii) ROC  $|Z|<0.5$ . (08 Marks)
- 8 a. State and prove the following properties of z transform
- Differentiation in z domain
  - Scaling in z domain. (06 Marks)
- b. A linear LTI system is characterized by the system function :
- $$H(z) = \frac{3-4z^{-1}}{1-3.5z^{-1}+1.5z^{-2}}$$
- specify ROC of H(z) and determine h[n] for :
- Stable system
  - Causal system (06 Marks)
- c. A discrete LTI system is characterized by the following difference equation :
- $$y[n] - y[n-1] - 2y[n-2] = x[n]$$
- with input  $x[n] = 6u[n]$  and the initial conditions are  $y(-1) = -1, y(-2) = 4$
- Find the zero input response – ZIR
  - Find the zero state response – ZSR
  - Find the total response. (08 Marks)

\* \* \* \* \*